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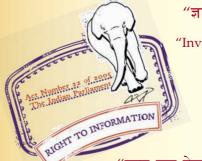
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IS 4988-4 (1968): Glossary of terms and classification of earth moving machinery, Part 4: Excavators [MED 7: Material Handling Systems and Equipment]





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# Indian Standard

# GLOSSARY OF TERMS AND CLASSIFICATION OF EARTH-MOVING MACHINERY

# PART IV EXCAVATORS (First Reprint FEBRUARY 1981)

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## Indian Standard

## GLOSSARY OF TERMS AND CLASSIFICATION OF EARTH-MOVING MACHINERY

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## Indian Standard

## GLOSSARY OF TERMS AND CLASSIFICATION OF EARTH-MOVING MACHINERY

#### PART IV EXCAVATORS

## 0. FOREWORD

**0.1** This Indian Standard (Part IV) was adopted by the Indian Standards Institution on 30 December 1968, after the draft finalized by the Construction Plant and Machinery Sectional Committee had been approved by the Civil Engineering Division Council.

**0.2** Earth-moving plant and machinery is being extensively used on all major irrigation projects, road construction, land reclamation and other tests involving removal and shifting of earth. Earth-moving machine has been in production in the country for over a number of years and the requirements have increased considerably in the last few years due to the overall increase in the development work and this has resulted in many manufacturers switching over their production to earth-moving plant and machinery. With the increasing use and manufacture of earth-moving machinery in the country it has been considered necessary by the Construction Plant and Machinery Sectional Committee to lay down the guide lines for present and future manufacture to ensure that there is standardization in the equipment under production or likely to be produced in future in the country.

**0.2.1** As a first step towards this end, a glossary of terms relating to earth moving machinery has been prepared with a view to unifying the various technical terms and expressions in connection with the manufacture and use of such machinery. This standard does not cover the requirements relating to design, manufacture and testing of equipment, which will be covered subsequently in separate standards.

**0.3** For convenience of reference, the standard has been divided into five parts. IS: 4988 (Part I)-1969\* covers the definitions for the terms applicable in general to all types of earth moving machinery and not specifically to any one equipment.

\*Glossary of terms and classification of earth-moving machinery: Part 1 General terms.

**0.3.1** The terms applicable to a specific type of machinery are covered in separate parts as below:

- IS: 4988 (Part II)-1968 Glossary of terms and classification of earthmoving machinery: Part II Dozers
- IS: 4988 (Part III)-1968 Glossary of terms and classification of earthmoving machinery: Part III Motor and towed scrapers.
- IS: 4988 (Part IV)-1968 Glossary of terms and classification of earthmoving machinery: Part IV Excavators
- IS: 4988 (Part V)-1968 Glossary of terms and classification of earthmoving machinery: Part V Motor graders

**0.4** In the formulation of this standard, due weightage has been given to international co-ordination among the standards and practices prevailing in different countries in addition to relating it to the practices in the field in this country.

**0.4.1** While formulating this standard, due consideration has also been given to the type of equipment on the future plan of production by various manufacturers. In deciding the size and output of different types of machinery, for example, dozers, scrapers, motor graders and excavators, it has been kept in view that the power for prime mover required for different categories of equipment is similar. It has been endeavoured that a prime mover which is used for light dozer would also be suitable to provide power for light motor grader or a light excavator.

#### 1. SCOPE

1.1 This standard (Part IV) gives definitions of terms applicable exclusively to excavators. This standard also lays down the classification and method to be adopted in calculating the output of excavators.

Note — The definitions of terms applicable in general to all types of earth-moving machinery are covered in IS: 4968 ( Part I )-1969\*.

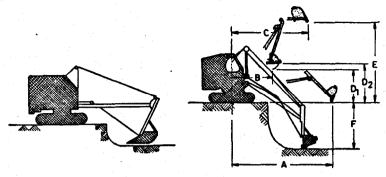
#### 2. DEFINITIONS

2.1 Back Hoe — Equipment fitted to an excavator base machine that digs by pulling a boom handle mounted bucket towards itself (see Fig. 1).

#### 2.2 Boom

2.2.1 Boom Live — A shovel boom which can be fitted and lowered without interrupting the digging cycle.

\*Glossary of terms and classification of earth-moving machinery: Part I General terms.



- **A** Maximum digging radius
- **B** Radius at beginning of dump

C Radius at end of dump

- D<sub>1</sub> Dumping height at beginning of dump (For bottom door bucket)
- D<sub>2</sub> Dumping height at beginning of dump (For hoe Bucket)
  - E Dumping height at end of dump

F Maximum digging depth

#### FIG. 1 MACHINE CHARACTERISTICS OF EXCAVATORS WITH BACK HOE EQUIPMENT

2.2.2 Boom Length—It is the distance measured between the axis of the boom foot pivot and the axis of the top load block pivot pin.

#### 2.3 Capacity

2.3.1 Capacity Heaped — Heaped capacity shall be based upon the physical dimensions of the bucket, with the soil at 2:1 angle of repose. If on measuring the heaped capacity of a bucket, it is found that the value falls below a given rating interval by more than 2 percent the next lower interval shall be deemed as the rating.

2.3.2 Capacity Struck — It is the quantity of material retained in the bucket after a heaped load is struck by drawing a straight edge along the width of the bucket.

NOTE - Teeth will not be taken into account when calculating the struck capacity.

2.4 Clamshell — Twin jawed bucket without teeth used with crane jib on excavator base machine for loading soft material (see Fig. 2).

2.5 Crane Equipment — A jib and crane hook fitted to an excavator base machine.

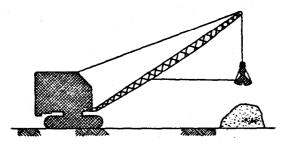


FIG. 2 CLAMSHELL

**2.6 Crowd**— The process of forcing the bucket to dig or the mechanism which does the forcing.

#### 2.7 Digging

2.7.1 Digging Depth Maximum—It is the maximum depth below the ground on which the machine is standing, to which it can dig.

2.7.2 Digging Height Maximum — It is the height from the ground on which the machine is standing to the highest point to which the machine can dig.

2.7.3 Digging Line — On a shovel, the cable which forces the bucket into the soil called crowd in dipper shovel, drag in back hoe and dragline, and closing line in a clamshell.

2.7.4 Digging Radius Maximum — It is the distance from the axis of rotation of turn table to the farthest point the machine can dig.

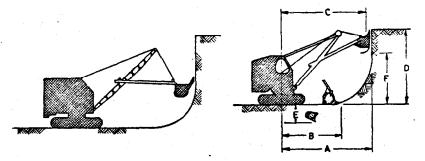
**2.8 Dipper Shovel**—Boom handle and bucket fitted to an excavator base machine for excavation from an exposed face above track level (see Fig. 3).

**2.9 Drag**—Pulling a bucket to dig or the mechanism by which the pulling is done or controlled.

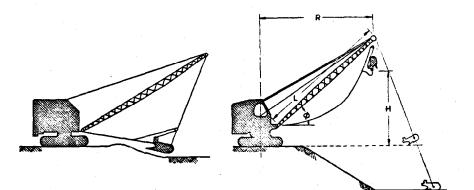
2.9.1 Dragline — Equipment fitted to an excavator base machine with crane jib, ropes and a bucket, which digs, by pulling towards the base machine (see Fig. 4).

#### 2.10 Dumping

2.10.1 Dumping Height Maximum — It is the height from the ground on which the machine is standing to the lower-most position of the bucket while discharging its lead, when the boom is at maximum elevation.



- A Maximum cutting radius, overall
- B Maximum cutting radius, at floor
- C Maximum dumping radius
- D Maximum cutting height, bank
- E Maximum cutting height, ditch
- F Maximum dumping height
- FIG. 3 MACHINE CHARACTERISTICS OF EXCAVATOR WITH DIPPER-SHOVEL EQUIPMENT



- Boom angle
- H Maximum dumping height
- L Length of boom
- **R** Working radius

FIG. 4 MACHINE CHARACTERISTICS OF EXCAVATORS WITH DRAGLINE EQUIPMENT

2.10.2 Dumping Radius — The distance from the axis of rotation of the turn table to the edge of the teeth of the bucket in the discharge position.

**2.11 Excavator** — Tracked or wheeled prime mover consisting of a revolving superstructure mounted on the base to which a variety of front end excavating and lifting equipment can be fitted.

2.12 Hoist Line — The mechanism by which a bucket or blade is lifted or the process of lifting it.

2.13 Jack Boom — A boom which supports sheaves between hoist drum and main boom.

2.14 Jib Boom — An extension piece hinged to the upper end of crane boom.

2.15 Optimum Depth of Cut — It is the depth of cut at which the maximum output is obtained and at which the dipper shovel comes up with a full load without undue crowding, in a single cut, up the face.

2.16 Retract Line — A mechanism by which a dipper shovel bucket is pulled back out of the digging.

2.17 Side Casting — Piling spoil alongside the excavation from which the excavator takes its load.

**2.18 Skimmer** — A bucket, mounted with rollers on a boom fitted to an excavator base machine, which can excavate above, at the level of or slightly below tracks, by sliding the bucket forward on the boom (see Fig. 5).

2.19 Swing Angle—The angle in degrees which the shovel shall swing between digging and dumping points.

#### **3. EXCAVATOR CAPACITY**

**3.1** The capacity of excavator shall be expressed in terms of rated capacity of the bucket which will be the heaped capacity and shall be expressed in cubic metres.

Note — Actual capacity of an excavator to handle a particular load in the bucket would depend upon the cutting radius at a particular angle of the boom. This needs to be correlated with the capacity of the bucket.

#### 4. CLASSIFICATION

**4.1** The excavators shall be classified into the following classes on the bucket capacity of the attachments fitted:

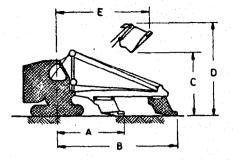
Class

Heaped Capacity of Bucket

 $m^3$ 

From 0.80 to 1.50 From 1.50 to 2.50 Over 2.50

Light Medium Heavy



- **A** Cutting radius minimum
- **B** Cutting radius maximum
- C Maximum dumping height
- D Clearance over boom at maximum dumping height
- E Dumping radius at maximum height

#### FIG. 5 MACHINE CHARACTERISTICS OF EXCAVATORS WITH SKIMMER EQUIPMENT

#### 5. EXCAVATOR OUTPUT

5.1 To find out the output of an excavator it is essential to know what is cycle of operation of excavator.

5.1.1 Cycle of Operation — An excavator, with any front and equipment, works in a definite cycle of load — swing to discharge, discharge, and swing back to re-load.

5.1.2 Cycle Time — The time taken to complete this cycle depends not only on type of soil and angle of swing but also on the mechanism of controls on the machine concerned. Tabulated values of cycle time can only therefore be taken as an average. Average cycle times for an excavator are shown in Table 1 for different types of soil. These timings are based on 90° angle of swing. Cycle times for grabs and clamshells vary so greatly with the type of work being done that no reliable figures can be given.

#### TABLE 1 CYCLE TIMES FOR DIPPER SHOVELS, DRAGLINES, BACK HOES AND SKIMMERS

(Clauses 5.1.2 and 5.2.1)

SL	EQUIPMENT	CAPACITY	CYCLE TIME ( IN SECONDS )*			
No.		(m²)	Easy Digging (Light Moist Clay or Loam)	Medium Digging (Loam)	Hard Digging (Hard Tough Clay)	
(1)	(2)	(3)	(4)	(5)	(6)	
		0·29	15	18	24	
		0.38	15	18	24	
		0-57	18	20	26	
i)	Dipper shovel (90° swing)	0.77	18	20	26	
,		0.96	18	20	26	
		1.12	18	20	26	
		1.53	18	20	26	
	с	0.29	20	2 <del>4</del>	30	
		0.38	20	24	30	
		0-57	22	26	32	
ii)	Dragline (90° swing)	0-77	24	28	35	
		0.96	24	28	35	
		1-15	24	28	35	
		1.53	<b>2</b> 8	33	40	
		0.29	16	20	26	
	· ·	0.38	- 17	20	26	
		0-57	20	22	28	
iii)	Back hoe (90° swing)	0.77	20	22	28	
		0-96	20	22	29	
		1.15	20	22	29	
		1.53	20	22	29	
		0-29	19	22	30	
		0.38	19	23	30	
		0.57	22	25	32	
iv)	Skimmer	0.77	22	25	32	
		0.96	23	25	33	
		1.15	23	25	33	
		1.53	23	25	33	

\*For each increase of 10° in swing add 2 seconds to cycle time, for each decrease of 10° in swing subtract 2 seconds from cycle time.

#### 5.2 Calculation of Output

5.2.1 The output of excavator shall be calculated from the following formula:

$$\text{Output} = \frac{3600 \times Q \times f \times E \times k}{C} \quad \text{m}^{3}/\text{ hour}$$

where

Q = rated capacity of buckets (m<sup>3</sup>) in loose measure;

- f =soil factor. The bucket will handle earth in loose measures. To obtain equivalent bank measure apply a soil conversion factor (see Table 2);
- E = a factor combining operator efficiency and task efficiency. Average operator efficiency is 75 percent. Task efficiency for excavators shall be obtained from Table 3;
- k = this factor makes allowance for the effect, on the rated bucket capacity, of different types and conditions of soil (see Table 4); and

C = cycle time in seconds (see Table 1).

#### TABLE 2 SOIL CONVERSION FACTORS

SL	MATERIAL	STATE		CONVERT TO	
No.			Bank	Loose	Compacted
(1)	(2)	(3)	(4)	(5)	(6)
· i)	Sand	Bank	1-00	1-00	0.92
·		Loose	1.00	1.00	0.92
		Compacted	1.09	1.09	1-00
ü)	Common earth	Bank	1.00	1-05	0-88
		Loose	0-95	1.00	0-84
•		Compacted	1.14	1-19	1.00
iii)	Clay	Bank	1.00	1.20	0.80
•		Loose	0-83	1.00	0.75
		Compacted	1.11	1.33	1-00
iv)	Rock	Bank	1.00	1.50	1-40
•		Loose	0.67	1.00	0.93
		Compacted	1-11	1-07	1-00

	TABLE 3 TA	SK EFFICIENCY FACTOR	FOR EXCAVAT	ORS	
	· •	(Clause 5.2.1)			
SL No.	FRONT END EQUIP- MENT IN USE	TABE	TASK EFFICIENCY FACTOR		
190.	MENT IN USE		When Loading into Haulage Vehicle	When Side- Casting	
(1)	(2)	(3)	(4)	(5)	
i)	Dipper shovel	Excavation above track level:			
		Little movement	0-65	0.8	
		Much movement	0.45	0.6	
		When using timber mats	<del>0·4</del> 5	0.6	
		Working in shattered rock at quarry face (delays due to blasting)	0.4	0.6	
ü)	Back hoe	Trenching:			
		Trench of bucket width	0-8	1.0	
		Trench wider than bucket	0.6	0.2	
iii)	Dragline	Excavation below track level:			
		Bulk excavation	0.8	1.0	
	•	Excavating wide, open ditches	0.7	0-9	
iv)	Skimmer	Excavation of shallow sur- face cut above track level	0.7	1.0	

5.3 Optimum Depth of Cut — The above calculation assumes a  $90^{\circ}$  swing of the boom from load to discharge and an optimum depth of cut. The optimum depth of cut is the distance the bucket travels excavating in each sweep. If the cut is shorter or longer than the optimum, output is reduced.

5.3.1 If the swing of the boom is greater than 90°, the output is reduced as the cycle time lengthens by 2 seconds for each 10° of increase. Reduction of swing increases output, the cycle time being shortened by 2 seconds by each 10° swing below 90°.

### TABLE 4 EXCAVATOR BUCKET EFFICIENCY FACTORS

(Clause 5.2.1)

Sl	MATERIAL		BUCKET EFFICIENCY FACTOR		
No.			Dipper Shovel	Dragline	
(1)		(2)	(3)	(4)	
i)	Easy	digging:			
	a)	Loose, soft, free-running material	0.95 to 1.00	0.95 to 1.00	
	b)	Close-lying material which fills bucket and often provides heaped loads			
	<b>c</b> )	Overloads compensate for swell of material			
	<b>d</b> )	Dry or moist sand, small gravel, loose earth, sandy clay cinders of ashes, well blasted material			
ii)	Medu	um digging:			
	<b>a</b> )	Harder material that does not require blast- ing, but breaks up with bulkiness causing voids in bucket	0 <sup>.</sup> 85 to 0 <sup>.</sup> 90	0 <b>·80</b> to 0·90	
	b)	Dry or wet clay, coarse gravel, packed earth			
iii)	Media	um-hard digging:			
	a)	Material that requires some breaking up by blasting or shaking, but which is bulky and somewhat hard to penetrate causing voids in bucket	0.75 to 0.80	0.65 to 0.75	
	b)	Well broken limestone, sand rock and other blasted rocks, blasted shale, heavy wet sticky clay, gravel with large boulders, cemented gravel			
iv)	Hard	digging:			
	<b>a</b> )	Blasted rock, hard pan, and other bulky material which is difficult to penetrate and leaves large voids in the bucket	0.50 to 0.70	0.40 to 0.65	
	b)	Hard tough shale, limestone, granite, sand- stone, conglomerate (all these blasted to large pieces and mixed with fines and dirt)			
	C)	Tough rubbery clay that shaves from the bank			

# INTERNATIONAL SYSTEM OF UNITS (SI UNITS)

### **Base Units**

Quantity	Unit	Symbol	
Length	metre	m	atter and the second second
Mass	kilogram	kg	
Time	second	5	
Electric current	ampere	A	1
Thermodynamic temperature	kelvin	K	
Luminous intensity	candela	cd	
Amount of substance	mole	mol	
Supplementary Units			
Quantity	Unit	Symbol	
Plane angle	radian	rad	
Solid angle	steradian	sr	
Derived Units			
Quantity	Unit	Symbol	Conversion
Force	newton	N	1 N = 1 kg.1 m/s <sup>2</sup>
Energy	joule	J	1 J = 1 N.m
Power	watt	W	$1 W = 1 J/s^{-1}$
Flux	weber	Wb	1 Wb = 1 V.s
Flux density	tesla	T	1 T = 1 Wb/m <sup>s</sup>
Frequency	hertz	Hz	1 Hz = 1 c/s ( $s^{-1}$ )
Electric conductance	siemens	S	1 S-1 A/V
Pressure, stress	pascal	Pa	1 Pa = 1 N/m <sup>a</sup>

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